

# GP-ALPS: Automatic Latent Process Selection for Multi-Output Gaussian Process Models



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- The choice of the **latent space** for multi-output GPs forms a **model selection problem**, with the usual challenges.
- GP-ALPS: **binary variables** automatically **select latent processes** that meaningfully contribute to explaining the data.
- Exact inference is **intractable**. We propose a mean-field **approximate inference** scheme using continuous relaxations.

## Motivation

- Gaussian processes commonly extended to multiple outputs by linearly combining latent GPs  $(x_j)_{j=1}^m$  via a “mixing matrix”  $H$ :  

$$x_j \sim \mathcal{GP}(0, k_j(t, t')), \quad f(t) = Hx(t), \quad y_i(t) \sim \mathcal{N}(f_i(t), \sigma_i^2).$$
- Choice of kernels and number of latent processes is important.
- Can this be done automatically?

## GP-ALPS

- A binary, multiplicative “switch”  $b_j$  for each latent process.
- Generative model:  

$$x_j \sim \mathcal{GP}(0, k_j(t, t')), \quad b_j \sim \text{Bern}(\theta_j), \quad H_{ij} \sim \mathcal{N}(0, s_{ij}),$$

$$f(t) = H(x(t) \circ b), \quad y_i(t) \sim \mathcal{N}(f_i(t), \sigma_i^2).$$
- Each of the  $2^m$  possible values of  $b$  corresponds to a model class.
- Bayesian Occam’s razor encourages parsimonious posterior over  $b$ .

## Approximate Inference Scheme

- Augment model with **inducing points**  $X^z$  [1].
- Introduce **structured mean-field approximation** of posterior:

$$q(X, X^z, H, b) = p(X|X^z)q(X^z)q(H)q(b).$$

- Relax  $p(b)$  and  $q(b)$  using the **Concrete distribution** [2]:

$$p(b) \approx \prod_{j=1}^m \text{Concrete}(b_j; \theta_j), \quad q(b) = \prod_{j=1}^m \text{Concrete}(b_j; \rho_j).$$

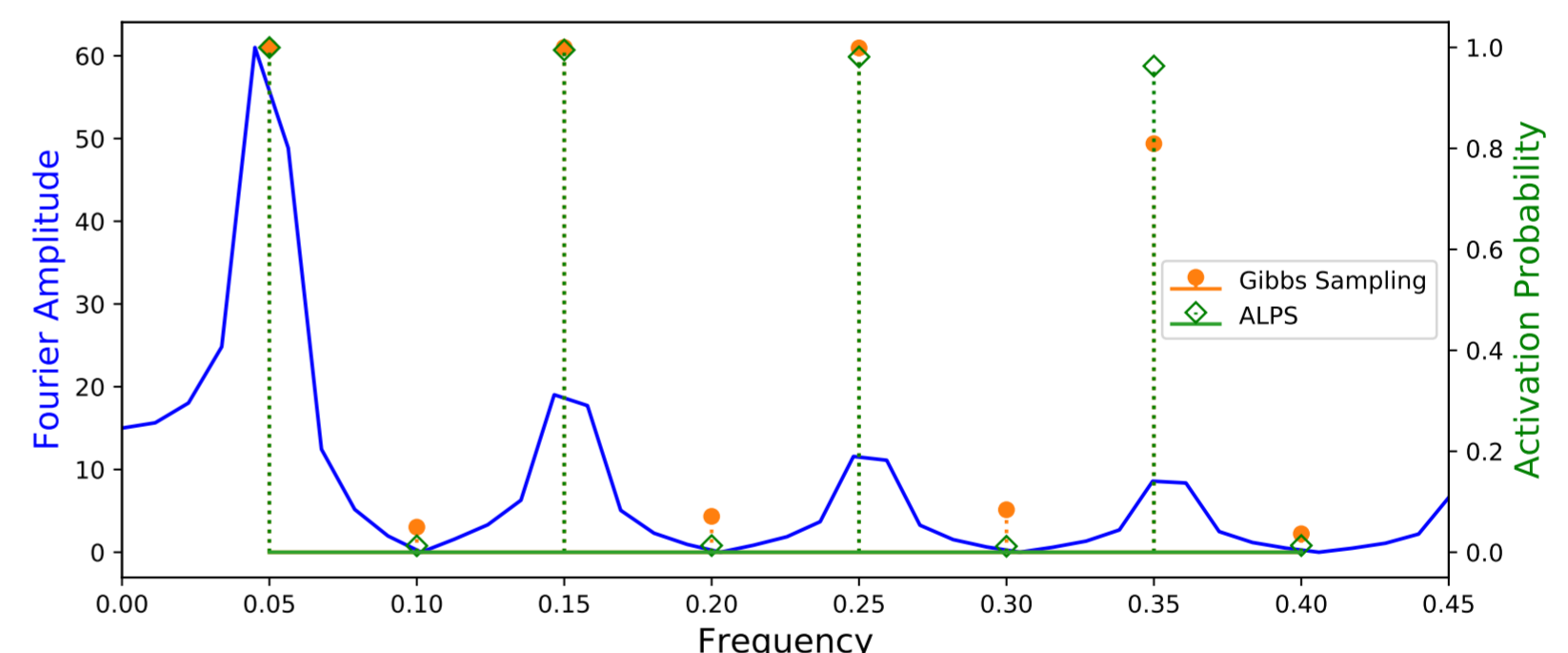
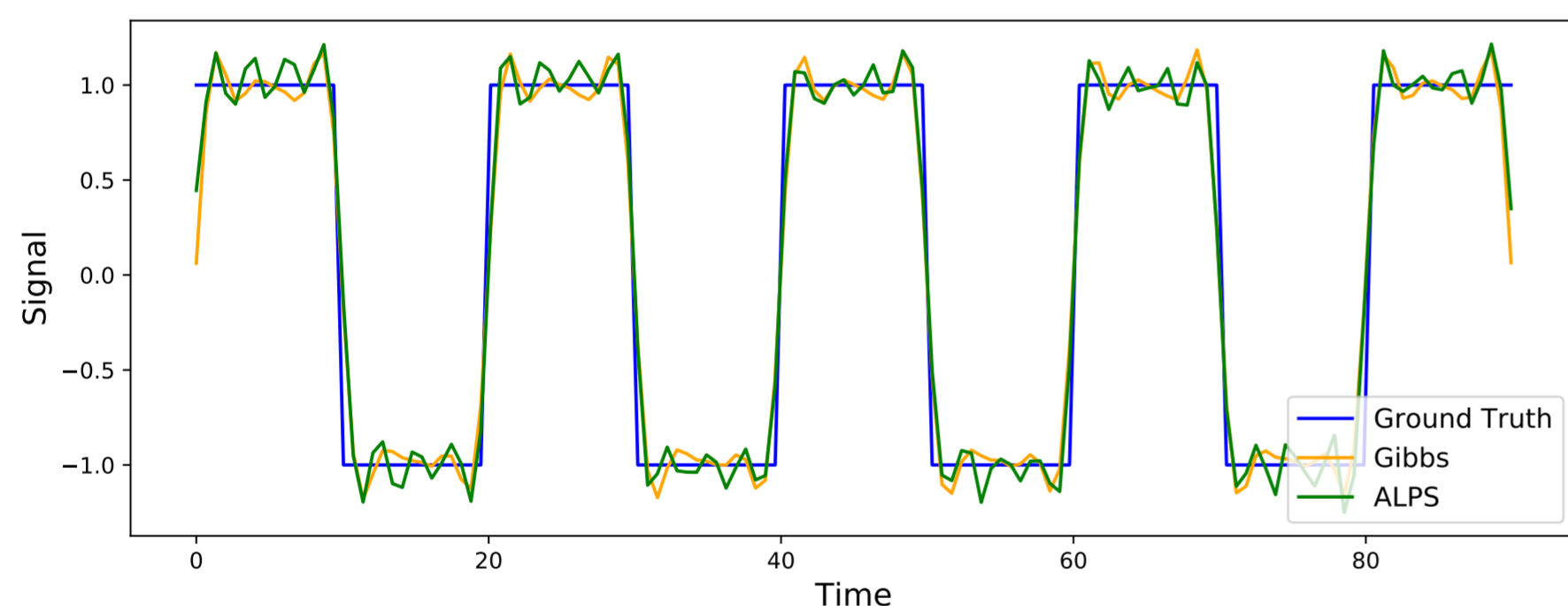
- Variational posterior  $q$  obtained by maximising the **evidence lower bound (ELBO)**

$$\log p(Y) \geq \mathcal{L} = \mathbb{E}_q \left[ \log \frac{p(Y, X, X^z, H, b)}{q(X, X^z, H, b)} \right]$$

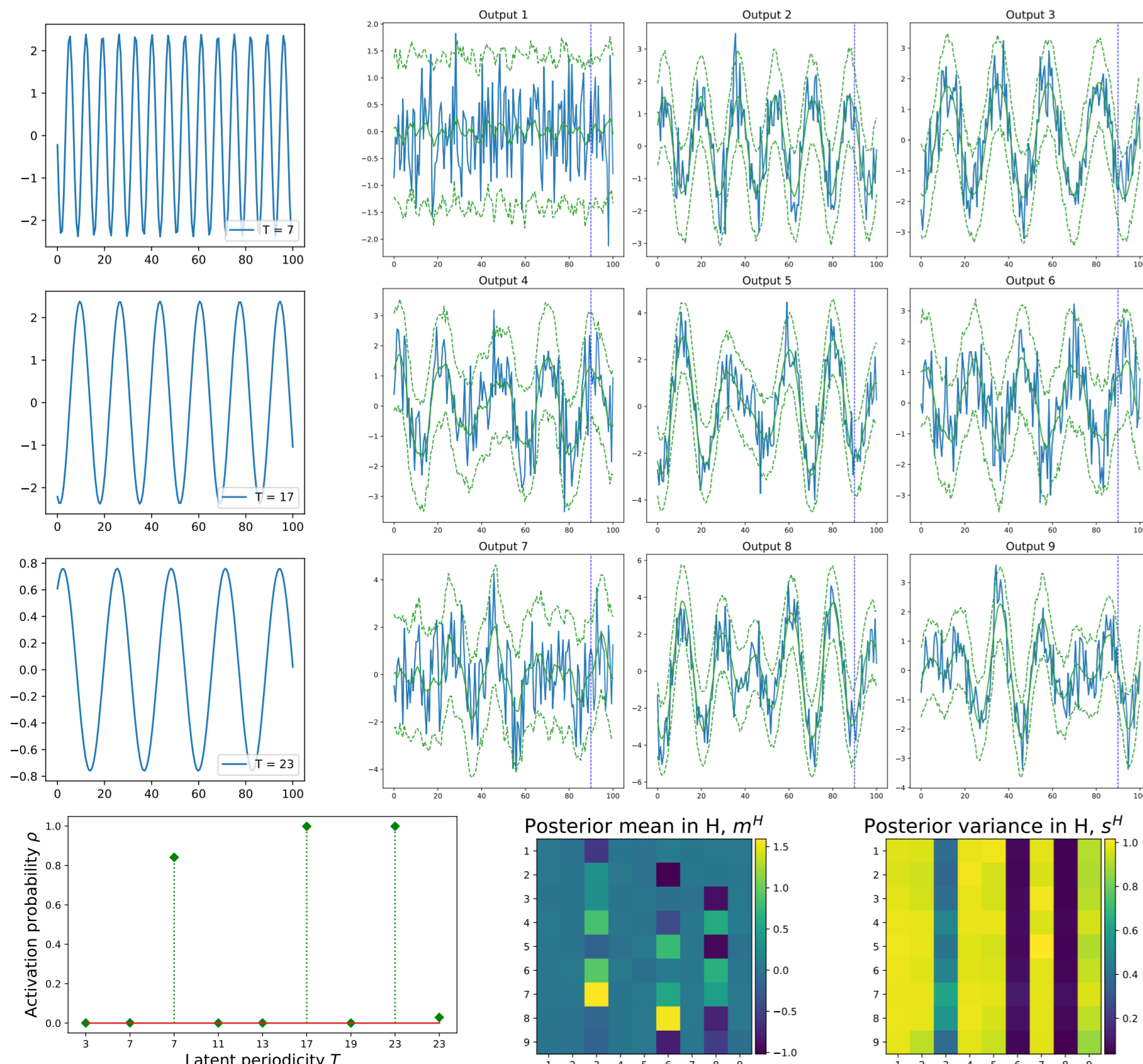
using stochastic, gradient-based optimisation in combination with the **reparametrisation trick** [3].

- ELBO is a sum over data points, hence **amenable to mini-batching** to scale to large datasets.

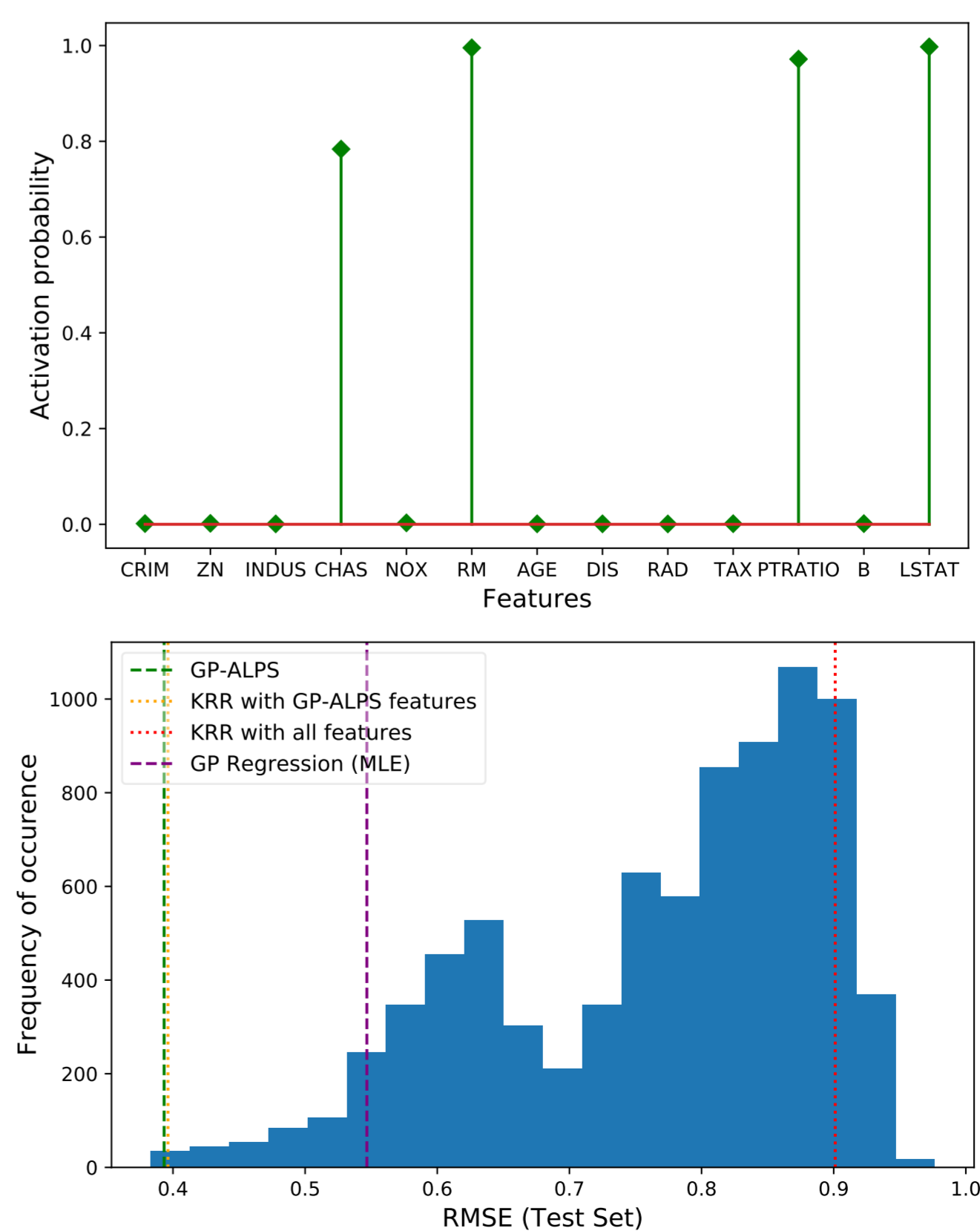
## Square Wave Decomposition



## Noisy Mixture of Sinusoids



## Boston Housing Dataset



[1] Dezfouli, Amir, and Edwin V. Bonilla. “Scalable inference for Gaussian process models with black-box likelihoods”, 2015.  
 [2] Maddison, Chris J., Andriy Mnih, and Yee Whye Teh. “The concrete distribution: A continuous relaxation of discrete random variables”, 2016.  
 [3] Kingma, Diederik P., and Max Welling. “Auto-encoding variational bayes”, 2013.